

User's Manual

PROGRAM

**Relocatable Math
Library File**

TAPES

Library Binary: 099-000001

093-000041-03

ABSTRACT

This document provides a brief description of all the routines available using Data General's math library tape 099-000001. These descriptions are in alphabetical order according to function. All the information necessary to CALL these routines is provided in this document.

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This revision of the Relocatable Math Library File manual, 093-000041-03, supersedes manual number 093-000041-02. For a description of the changes made in this revision, see the list of changes at the end of the manual.

INTRODUCTION

The following is a brief description of all the relocatable math library subroutines available on tape number 099-000001. These subroutines appear in alphabetical order according to function. Each description will elaborate on the items explained below.

- PURPOSE: Explains the function performed by the routine.
- TITLE: Gives the name of the routine (necessary for editing the library tape).
- ENTRY: Gives the name by which a routine is referenced in an .EXTN statement. This name is identical to the JSR entry point unless specified otherwise.
- INPUT: Describes necessary input format.
- OUTPUT: Describes results of the routine.

CALLING SEQUENCE AND ENTRY POINTS:

The relocatable routines contained in the math library are called by declaring the appropriate entry point as a normal external within the user program. For example, to call double precision absolute value:

```
                .EXTN      .DABS
                .
                .
                JSR        @DUMMY
                .
                .
DUMMY:          .DABS
```

The names of the entry point(s) are given for all routines, and unless otherwise noted all user calls must use the above method.

ERROR CONDITIONS:

Explains or cautions about the idiosyncrasies of the routine.

CARRY AND REGISTERS:

Gives states of active registers upon exit.

LENGTH AND TIME:

Gives the number of words used by this routine and an approximation of execution time. Unless otherwise noted, execution times are calculated for the Nova. To obtain approximate execution times for other Nova-family machines, use the following conversions:

.2 * Nova execution time \approx Supernova or Nova 800 execution times

.35 * Nova execution time \approx Nova 1200 execution time.

ALGORITHM:

Describes the method used to produce the desired result.

REFERENCE:

Cites literature that may be of use in obtaining further information.

PROGRAM LISTING:

An assembly listing of the routine is given.

In most instances there will be no ENTRY, ALGORITHM, or PROGRAM LISTING entries given. The ALGORITHM and PROGRAM LISTING entries will be included in future editions of this manual. ENTRY information is given only when the entry is different from the JSR entry point.

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PURPOSE:

This routine computes the absolute value of a fixed point, single precision, two's complement number.

TITLE:

The title is .ABS.

INPUT:

The input is a single precision number in AC0.

OUTPUT:

The absolute value of the input is returned in AC0.

CALLING SEQUENCE AND ENTRY POINT:

Indirect to .ABS with normal return to the instruction following the call.

ERROR CONDITIONS:

The absolute value of -2^{*15} cannot be represented and will be returned unchanged.

CARRY AND REGISTERS:

Carry and AC0 may be destroyed; AC1, AC2 and AC3 are unchanged.

LENGTH AND TIME:

This routine consists of 3 words and is normally relocatable.
For $X \geq 0$, execution time is 8.2 μ s.
For $X < 0$, execution time is 13.8 μ s.

ABSOLUTE VALUE

(Double Precision)

PURPOSE:

This routine computes the absolute value of a double precision, fixed point, two's complement number.

TITLE:

The title is .DABS.

INPUT:

A number in AC0 (high order), AC1 (low order).

OUTPUT:

The absolute value of the input returned in AC0, AC1 - high order in AC0, low order in AC1.

CALLING SEQUENCE AND ENTRY POINT:

Indirect at .DABS, with normal return to the instruction following the call.

ERROR CONDITIONS:

Caution: The absolute value of -2^{31} cannot be represented and is returned unchanged.

CARRY AND REGISTERS:

AC0, AC1, and Carry are destroyed; AC2 and AC3 remain unchanged.

LENGTH AND TIME:

This routine consists of 6 instructions and is normally relocatable.

For $X \geq 0$, execution is 8.2 μ s

For $X < 0$, execution is 19.4 μ s

PURPOSE:

This routine computes the sum of two double precision, two's complement integers.

TITLE:

The title is .DADD.

INPUT:

The first operand must be in AC0, AC1 (high order, low order). The second operand must be in storage, higher order word followed by lower order word. The address of the higher order word of the second operand must be given after the JSR @DUMMY.

OUTPUT:

The double precision sum will be returned in AC0, AC1 (high order, low order).

CALLING SEQUENCE AND ENTRY POINT:

Indirect at .DADD, then address of second operand with return to the instruction following the second operand address.

ERROR CONDITIONS:

Caution: No check is made for overflow.

CARRY AND REGISTERS:

AC0, AC1, AC3 and Carry are destroyed; AC2 remains unchanged.

LENGTH AND TIME:

This routine consists of 15 (octal) instructions and is normally relocatable.
Execution time is 54.9 μ s.

ARCTANGENT

(Single Precision)

PURPOSE:

To calculate the fixed point arctangent of the quotient of two input arguments.

TITLE:

ATANX

ENTRY:

.ATANX

INPUT:

Argument dividend in AC0, argument divisor in AC1.
Both arguments are expressed in radians in the following format:

sign	integer	fraction
bit 0	bits 1 and 2	bits 3 through 15

The sign bit is set to a 1 only if the argument is negative.

OUTPUT:

The result x , expressed in radians, falls in the range $-\pi \leq x \leq \pi$. The result, in AC2, is given in the same format as that described for input arguments.

CALLING SEQUENCE:

JSR indirect through page zero entry .ATANX . Return is to the next sequential location following the call.

ERROR CONDITIONS:

None; all input arguments will be interpreted in the format illustrated above.

CARRY AND REGISTERS:

AC0 and AC1 are saved; AC3 and Carry are destroyed.

LENGTH AND TIME:

One ZREL and 100 octal NREL locations. Average execution time on the NOVA 1200 is 1.3 ms.

ALGORITHM:

The quotient of the input arguments, x , is found by means of a call to the unsigned integer divide routine, DVD. For the range $0 \leq x \leq 1$, the arctangent of x is calculated to be equal to $x * P(x^2)$. Calls to the unsigned integers multiply routine (.MPYU) and Polynomial expansion function (.POLY) are made. A sixth order polynomial is computed, $P(x^2) = P_0 + P_1 x + P_2 x^2 \dots + P_6 x^6$, with the following coefficients:

$$\begin{aligned} P_0 &= .99999 \\ P_1 &= - .33326 \\ P_2 &= .19881 \\ P_3 &= - .13487 \\ P_4 &= .83871 * 10^{-1} \\ P_5 &= .37012 * 10^{-1} \\ P_6 &= .78633 * 10^{-2} \end{aligned}$$

For other values of x , one of the following quadrant adjustments is made, where m and n represent the original arguments input in AC0 and AC1 respectively.

$$\text{ARCTAN} \left(\frac{+m}{+n} \right) = \pi/2 - \text{ARCTAN} \left(\frac{n}{m} \right)$$

$$\text{ARCTAN} \left(\frac{-m}{+n} \right) = -\text{ARCTAN} \left(\frac{m}{n} \right)$$

$$\text{ARCTAN} \left(\frac{+m}{-n} \right) = \pi - \text{ARCTAN} \left(\frac{m}{n} \right)$$

$$\text{ARCTAN} \left(\frac{-m}{-n} \right) = - \left(\pi - \text{ARCTAN} \left(\frac{m}{n} \right) \right)$$

REFERENCE:

John F. Hart, "Computer Approximations" New York: John Wiley & Sons, Inc., 1968; pages 128 - 129, INDEX 4990

ARCTANGENT (cont'd)

(Single Precision)

PROGRAM LISTING:

```

;          FIXED POINT ARCTAN(OFF TWO ARGUMENTS)
      .TITLE  ATANX
      .EN1    .ATANX
      .EXTD   .POLY, MPYU
      .EXTN   DVD

      .EREL
00000-000007' .ATANX: ATANX
      .NRREL

00000'000000 RTURN: 0
00001'000000 SAV0: 0
00002'000000 SAV1: 0
00003'000000 SAV2: 0
00004'000000 SIGN: 0
00005'000000 COMPL: 0
00006'000000 SUPPL: 0

00007'054771 ATANX: STA      3,RTURN      ;SAVE RETURN ADDRESS
00010'040771 STA      0,SAV0      ;SAVE AC0,1
00011'044771 STA      1,SAV1
00012'101120 MOVEL    0,0          ;GET SIGN
00013'152560 SUBCL    2,2          ;IN AC2
00014'050770 STA      2,SIGN          ;SAVE IT
00015'125120 MOVEL    1,1          ;SAVE SIGN OF AC1
00016'152560 SUBCL    2,2          ;AS SUPPLIMENT FLAG
00017'050767 STA      2,SUPPL
00020'176400 SUB      3,3          ;SET COMPLEMENT FLAG
00021'106432 SUBE#    0,1,SEC      ;IF AC0>AC1
00022'000404 JMP      .+4          ;AND SWAP ARGUMENTS
00023'111000 MOV      0,2
00024'175400 INC      3,3
00025'121001 MOV      1,0,SKP
00026'131000 MOV      1,2          ;AC0<=AC1
00027'054756 STA      3,COMPL
00030'112415 SUB#     0,2,SNR          ;CANNOT BE EQUAL
00031'151400 INC      2,2          ;AC0/AC2 < 1
00032'126400 SUB      1,1
00033'177777 DVD              ;GET AC0/AC2
00034'131000 MOV      1,2
00035'006002S JSR     0,MPYU          ;GET X**2
00036'050745 STA      2,SAV2
00037'111000 MOV      0,2
00040'020430 LDA      0,ATNCF      ;POINT ARCTAN COEFF.S
00041'024426 LDA      1,ATCFCT    ;ARCTAN COEFF COUNT
00042'006001S JSR     0,POLY          ;EVALUATE POLYNOMIAL

```

PROGRAM LISTING:

```

00043'030740 LDA 2,SAV2
00044'006002S JSR 0,MPYU ;GET X*P
00045'014740 DSZ COMPL ;COMPLEMENT ANGLE?
00046'000404 JMP .+4 ;DO NOT COMPLEMENT
00047'024417 LDA 1,PI.2 ;PI/2
00050'106400 SUB 0,1 ;PI.2-X*P
00051'121000 MOV 1,0
00052'101220 MOVZK 0,0
00053'014733 DSZ SUPPL ;SUPPLIMENT?
00054'000404 JMP .+4 ;NO
00055'105000 MOV 0,1
00056'020410 LDA 0,PI.2
00057'122400 SUB 1,0 ;PI-ANGLE
00060'024724 LDA 1,SIGN
00061'125220 MOVZK 1,1 ;GET SIGN
00062'111200 MOVK 0,2 ;BIT IN
00063'020716 LDA 0,SAV0 ;RESTORE ACC,1
00064'024716 LDA 1,SAV1
00065'002713 JMP 0,RTURN

00066'144417 PI.2: 144417 ;PI/2 1.44417 OCTAL
00067'000006 ATCFCT: 6
00070'000071' ATNCF: .+1
00071'000402 402 ;.78633 7627 -2
00072'175502 -2276 ;-.37012 99998 -1
00073'005275 5275 ;.83871 18962 -1
00074'167274 -10504 ;-.13487 19133
00075'014563 14563 ;.19881 48243 4
00076'152527 -25251 ;-.33326 51491 7
00077'077777 77777 ;.99999 93478 2
  
```

.END ;END OF ARC TAN

BCD to BINARY
(Single Precision)

PURPOSE:

This routine converts a single precision number in BCD to binary.

TITLE:

The title is .BCDB.

INPUT:

A BCD integer in AC1 (maximum value 9999 decimal).

OUTPUT:

Binary equivalent of BCD integer is returned in AC1.

CALLING SEQUENCE AND ENTRY POINT:

Indirect at .BCDB with normal return to the instruction following the call.

ERROR CONDITIONS:

If a digit greater than binary 1001 is encountered in the input, Carry will be set, AC1 will be unchanged, and AC0 will contain the bad digit. Otherwise, Carry will be zero on return.

CARRY AND REGISTERS:

AC0, AC1, AC3, and Carry are destroyed; AC2 is unchanged.

LENGTH AND TIME:

This routine consists of 53 (octal) words and is normally relocatable.

Execution time is 1.034 m.s.

PURPOSE:

This routine converts a double precision number in BCD to binary.

TITLE:

The title is .DBC.B.

INPUT:

A double precision integer is passed in AC0, AC1 (high order, low order) of maximum value of 99999999 decimal.

OUTPUT:

The binary equivalent of the input is returned in AC0, AC1 (high order, low order).

CALLING SEQUENCE AND ENTRY POINT:

Indirect at .DBC.B with normal return to the instruction following the call.

ERROR CONDITIONS:

If a digit greater than 9 is encountered in the input, Carry will be set and AC0 will contain the bad digit. Otherwise, Carry will be zero.

CARRY AND REGISTERS:

AC0, AC1, AC3, and Carry are destroyed; AC2 is unchanged.

LENGTH AND TIME:

This routine consists of 76 (octal) words and is normally relocatable.
Execution time is 2.174 ms.

BINARY TO BCD

(Single Precision)

PURPOSE:

This routine converts a binary number to its BCD equivalent.

TITLE:

The title is .BBCD.

INPUT:

An unsigned binary number in AC1.

OUTPUT:

The BCD equivalent in AC1.

CALLING SEQUENCE AND ENTRY POINT:

Indirect to .BBCD with normal return to the instruction following the call.

ERROR CONDITIONS:

If a number greater than 9999 is input for conversion, no conversion will take place and Carry will be set. Otherwise, Carry will be zero.

CARRY AND REGISTERS:

AC1, AC3 and Carry are destroyed; AC0, and AC2 are unchanged.

LENGTH AND TIME:

This routine is 41 (octal) words and is normally relocatable.
Execution time is $273.8 + N * 14.1 \mu s$ where N is the sum of the digits of the result.

PURPOSE:

This routine converts a double precision binary number to a BCD number.

TITLE:

The title is .DBBC.

INPUT:

A positive, double precision binary number in AC0, AC1 (high order, low order).

OUTPUT:

The BCD equivalent is in AC0, AC1 (high order, low order).

CALLING SEQUENCE AND ENTRY POINT:

Indirect to .DBBC with normal return to the instruction following the call.

ERROR CONDITIONS:

If AC0, AC1 contains a number greater than 99999999, no conversion will take place and Carry will be set. Otherwise, Carry will be reset.

CARRY AND REGISTERS:

AC0, AC1, AC3, and Carry are destroyed; AC2 is unchanged.

LENGTH AND TIME:

This routine consists of 57 (octal) words and is normally relocatable.

BINARY to DECIMAL

(Single Precision)

PURPOSE:

This routine converts a single precision two's complement number to an ASCII character string.

TITLE:

The title is .BIND.

INPUT:

A single precision, two's complement integer is passed in AC1.

OUTPUT:

An ASCII character string terminated by a null word. Characters are passed right adjusted in AC0 to the routine whose address must be in ZREL location .PTCH. The string is of the form:

 +DDDDD(NULL)
 or
 -DDDDD(NULL)

CALLING SEQUENCE AND ENTRY POINT:

Indirect at .BIND with normal return to the instruction following the call.

CARRY AND REGISTERS:

AC1, AC3 and Carry are destroyed; AC0 and AC2 remain unchanged.

LENGTH AND TIME:

This routine consists of 51 (octal) words and is normally relocatable.

Execution time is $(378.3 + N * 14.1) \mu s$ where N is the sum of the digits of the result.

PURPOSE:

This routine converts a double precision two's complement number to an ASCII decimal character string.

TITLE:

The title is .DBD.

INPUT:

A double precision, two's complement integer is passed in AC1, AC2 (high order, low order).

OUTPUT:

ASCII character string of the form:

or +DDDDDDDDDD(NULL)
-DDDDDDDDDD(NULL)

is outputted. Characters are passed right adjusted, bit 8 = 0, in AC0 to a user routine whose address must be stored in ZREL location .PTCH.

CALLING SEQUENCE AND ENTRY POINT:

Indirect to .DBD with normal return to the instruction following the call.

CARRY AND REGISTERS:

AC1, AC2, AC3, and Carry are destroyed; AC0 remains unchanged.

LENGTH AND TIME:

This routine consists of 112 (octal) words and is normally relocatable.

Execution time is $1.061 + N * .047$ ms where N is the sum of the digits of the result.

BINARY to GRAY CODE

PURPOSE:

This routine computes the Gray Code equivalent of a 16-bit binary word.

TITLE:

The title is .BGRY.

INPUT:

A binary word in AC0.

OUTPUT:

Gray Code equivalent in AC0.

CALLING SEQUENCE AND ENTRY POINT:

Indirect to .BGRY with normal return to the instruction following the call.

CARRY AND REGISTERS:

AC0, AC3, and Carry are destroyed; AC1, AC2 are unchanged.

LENGTH AND TIME:

This routine consists of 13 (octal) words and is normally relocatable.

Execution time is 50.3 μ s.

PURPOSE:

This routine converts a 16-bit binary word to an octal ASCII character string.

TITLE:

The title is .BINO.

INPUT:

A 16-bit binary number is passed in AC1.

OUTPUT:

An ASCII character string terminated by a null character. Characters are passed right adjusted in AC0 to the user routine whose address must be stored in ZREL location .PTCH. The string is of the form:

OOOOOO(NULL)

where "O" represents octal digits.

CALLING SEQUENCE AND ENTRY POINT:

Indirect to .BINO with normal return to the instruction following the call.

CARRY AND REGISTERS:

AC0, AC1, AC3, and Carry are destroyed; AC2 remains unchanged.

LENGTH AND TIME:

This routine consists of 27 (octal) words and is normally relocatable.

Execution time is $367.6 + N * 20.0 \mu s$, where N is the sum of the digits of the result (the sum expressed in decimal).

DECIMAL TO BINARY

(Single Precision)

PURPOSE:

This routine converts ASCII characters to a single precision binary number.

TITLE:

The title is .DBIN.

INPUT:

Input characters will be requested by calling a user "get a character" routine whose address must be stored in ZREL location .GTCH. This user routine must be provided. ASCII characters should be returned, right adjusted in AC0 with bit 8 = 0. This routine need not save any registers or Carry. Input should be in the form:

S D D . . . D D (break)

where "S" represents the sign ("- " or optionally "+"), D represents an ASCII decimal digit, and "break" is any ASCII character other than a digit.

OUTPUT:

Upon exit, AC0 will contain the ASCII break character and AC1 will contain the single precision, two's complement binary equivalent of the input.

CALLING SEQUENCE AND ENTRY POINTS:

Indirect to .DBIN with normal return to the instruction following the call.

If it is desired to output a signal character, the calling sequence is indirect to .DBNI. An ASCII "S" followed by a null character will be transmitted via AC0 to a "put a character" routine whose address must be in ZREL location .PTCH.

ERROR CONDITIONS:

Caution: The absolute value of the result is $N \text{ MOD } 2^{*15}$.
For example: +96741 converts to +31205.
-2^{*15} converts to 0.

CARRY AND REGISTERS:

AC0, AC1, and Carry are destroyed; AC2 and AC3 are unchanged.

LENGTH AND TIME:

This routine consists of 65 (octal) words and is normally relocatable. Execution time is approximately $110 + I * 82.2 \mu\text{s}$ where I is the number of digits in the input.

PURPOSE:

This routine converts ASCII characters to a double precision binary number.

TITLE:

The title is .DDB .

INPUT:

Input characters will be requested by calling a user "get a character" routine whose address must be stored in ZREL location .GTCH. This user routine must be provided. ASCII characters should be returned, right adjusted in AC0 with bit 8 = 0. This routine need not save any registers or Carry. Input should be in the form:

S D D . . . D D (break)

where "S" represents the sign ("- " or optionally "+"), D represents an ASCII decimal digit, and "break" is any ASCII character other than a digit.

OUTPUT:

Upon exit, AC0 will contain the ASCII break character. AC1 and AC2 contain the double precision two's complement equivalent of the input.

CALLING SEQUENCE AND ENTRY POINTS:

Indirect to .DDB with normal return to the instruction following the call.

To output a signal character, the call is indirect to .DDBI . This will cause an ASCII "D" followed by a null to be sent via AC0 to a "put a character" routine whose address must be stored in ZREL location .PTCH . This routine must accept ASCII characters in the same format as .GTCH .

ERROR CONDITIONS:

Caution: The absolute value of the result is $N \text{ MOD } 2^{**31}$. (see .DBIN).

CARRY AND REGISTERS:

All accumulators and Carry are destroyed.

LENGTH AND TIME:

This routine consists of 77 (octal) words and is normally relocatable. Execution time is approximately $69.90 + I * 43.35 \mu\text{s}$ on the Nova 1200, where I is the number of digits input.

Signed DIVIDE
(Single Precision)

PURPOSE:

Divides two fixed point , two's complement numbers.

TITLE:

The title is .DIV.

INPUT:

Dividend in AC0 (high order) and AC1 (low order).
Divisor in AC2.

OUTPUT:

Quotient in AC1. Remainder in AC0 (same sign as dividend).

CALLING SEQUENCE AND ENTRY POINT:

Indirect to .DIV with normal return to the instruction following the call.

ERROR CONDITIONS:

If the magnitude of the quotient exceeds $2^{15}-1$, Carry is set and the dividend remains unchanged. Otherwise, Carry will be zero.

CARRY AND REGISTERS:

AC0, AC1, AC3, and Carry are destroyed; AC2 remains unchanged.

LENGTH AND TIME:

This routine consists of 45 (octal) words and is normally relocatable.

Total average execution time is 605 μ s.

PURPOSE:

This routine calculates the quotient of two signed double precision numbers.

TITLE:

The title is DDIV.

INPUT:

The double precision divisor must be in AC0, AC1 (high order, low order). The quadruple precision dividend should be stored in four consecutive words, highest order to lowest order. AC2 must contain the address of the highest order word of the dividend.

OUTPUT:

The double precision quotient is returned in AC0, AC1 (high order, low order). Its sign is determined by the algebraic rules for signed division. The double precision remainder is stored in two consecutive memory words with the high order word first. AC2 will contain the address of the higher order remainder word. The sign of the remainder is the same as the sign of the dividend.

CALLING SEQUENCE AND ENTRY POINT:

Indirect to .DDIV with normal return to the instruction following the call.

ERROR CONDITIONS:

If the magnitude of the quotient would exceed $2^{*}31-1$ or $|\text{dividend}| > |\text{divisor}|$, an error condition exists, Carry is set, and return is made with unpredictable results.

CARRY AND REGISTERS:

All accumulators and Carry are destroyed.

LENGTH AND TIME:

This routine occupies 140 (octal) locations. Execution time is approximately 2.98 milliseconds.

REFERENCE:

"How to Use the Nova Computers", section 2.2.

Unsigned DIVIDE
(Single Precision)

PURPOSE:

To calculate the quotient of two unsigned integers.

TITLE:

DVD

ENTRIES:

DVD, .DIVI, .DIVU

INPUT:

If DVD or .DIVU entry, the dividend is input in AC0 (high order portion) and AC1 (low order portion). If .DIVI entry, the dividend is input in AC1 alone. In either case, the divisor is input in AC2.

OUTPUT:

The remainder is output in AC0, the quotient in AC1.

CALLING SEQUENCES:

The calling sequences consist of indirect calls through page zero entries .DIVI or .DIVU with return to the next sequential location following the call. DVD is equivalent to JSR @ .DIVU.

ERROR CONDITIONS:

Any inputs which would yield a quotient larger than $2^{16}-1$ (i. e. , $AC0 \geq AC2$) causes Carry to be set and return to be made to the caller. Otherwise Carry is reset.

CARRY AND REGISTERS:

AC2 is unchanged; AC0, AC1 and AC3 are destroyed under normal operation. AC1 is also left unchanged under error conditions, and Carry is always set or reset as discussed above.

LENGTH AND TIME:

Two ZREL locations and 21 octal NREL locations are required. Average execution times for .DIVI are 103 μ s on the Supernova and 545 μ s on the Nova. Average execution times for DVD are 102 μ s on the Supernova and 539 μ s on the Nova.

ALGORITHM:

. DIVI creates an all-zero high order dividend upon entry and then enters the DVD common logic.

DVD initially compares the divisor with the high order portion of the dividend. If that is greater than or equal to the divisor, the result would exceed $2^{16}-1$ and could not be represented in 16 bits using conventional two's complement notation. In this case Carry is set and return is made.

Otherwise, the less significant (LS) half of the dividend is shifted left, and 16₁₀ iterations of the following logic are performed. First the more significant (MS) half of the dividend (AC0) is shifted to the left and is compared to the divisor (AC2). If the divisor is equal to or less than the MS dividend, the divisor is subtracted from the MS dividend and the LS dividend (AC1) is shifted left. Otherwise, no subtraction is performed and only the LS dividend left shift is performed. In both cases, Carry contains the latest quotient bit and is shifted in behind the MS portion of the dividend when the iteration is repeated. Upon completion, the 16-bit quotient is entirely assembled in AC1, and the final adjusted dividend in AC0 is the remainder. The routine yields an exact answer.

REFERENCE:

"How to Use the Nova Computers", section 2.2 .

Unsigned DIVIDE (cont'd)
 (Single Precision)

```

                                .TITLE  DVD
                                .ENT    DVD,.DIVI,.DIVU

                                .ZREL
00000-000001'.DIVU:  DIVU
00001-000000'.DIVI:  DIVI

                                .NREL
006000-          DVD = JSR          @.DIVU

00000'102400 DIVI:  SUB 0,0          ; INTEGER DIVIDE, CLEAR AC0
00001'054416 DIVU:  STA 3,SAV3        ; SAVE AC3
00002'142432          SUBZ# 2,0,SZC   ; TEST FOR OVERFLOW
00003'000412          JMP DIVI        ; SET CARRY AND RETURN
00004'034414          LDA 3,M20       ; 16 ITERATIONS
00005'125120          MOVZL 1,1       ; SHIFT LOW DIVIDEND
00006'101100 DVD0:  MOVL 0,0         ; SHIFT HIGH DIVIDEND
00007'142412          SUB# 2,0,SZC   ; DOES DIVISOR GO IN?
00010'142400          SUB 2,0        ; YES
00011'125100          MOVL 1,1       ; SHIFT LOW DIVIDEND
00012'175404          INC 3,3,SZR    ; CHECK COUNT
00013'000773          JMP DVD0       ; NOT DONE
00014'176441          SUBO 3,3,SKP   ; DONE , CLEAR CARRY
00015'176420 DIVI:  SUBZ 3,3        ; SET CARRY
00016'002401          JMP @SAV3      ; RETURN

00017'000000 SAV3:  0                ; SAVE AC3

00020'177760 M20:  -20              ; - 16 DECIMAL

                                .END    ;END OF INTEGER DIVIDE

```

PURPOSE:

This routine computes the binary equivalent of a 16-bit Gray Code word.

TITLE:

The title is .GRYB.

INPUT:

Input is a Gray Code word in AC0.

OUTPUT:

The binary equivalent is returned in AC0.

CALLING SEQUENCE AND ENTRY POINTS:

Indirect to .GRYB with normal return to the instruction following the call.

CARRY AND REGISTERS:

AC0, AC3 and Carry are destroyed; AC1, AC2 are unchanged.

LENGTH AND TIME:

This routine consists of 22 (octal) words and is normally relocatable.

Execution time is 536.4 μ s.

Logical Exclusive OR

PURPOSE:

This routine computes the exclusive OR of two unsigned numbers.

TITLE:

The title is .XOR.

INPUT:

One 16-bit quantity is passed in AC0, the second in AC1.

OUTPUT:

The exclusive OR of the two quantities is returned in AC0.

CALLING SEQUENCE AND ENTRY POINT:

Indirect to .XOR with normal return to the instruction following the call.

CARRY AND REGISTERS:

AC0, AC3, and Carry are destroyed; AC1 and AC2 are unchanged.

LENGTH AND TIME:

This routine is 7 words and is normally relocatable.
Execution time is 34.0 μ s.

PURPOSE:

This routine computes the logical inclusive OR of two unsigned numbers.

TITLE:

The title is .OR .

INPUT:

One 16-bit quantity is passed in AC0, the second in AC1.

OUTPUT:

The inclusive OR of the two quantities is returned in AC0.

CALLING SEQUENCE AND ENTRY POINT:

Indirect to .OR with normal return to the instruction following the call.

CARRY AND REGISTERS:

AC0 is destroyed; AC1, AC2, AC3, and Carry are unchanged.

LENGTH AND TIME:

This routine consists of 5 words and is normally relocatable. Execution time is 25.6 μ s.

Signed MULTIPLY

(Single Precision)

PURPOSE:

This routine multiplies two, fixed point, single precision, two's complement numbers.

TITLE:

The title is .MPY.

INPUT:

One fixed point, single precision operand is passed in AC1, the second in AC2.

OUTPUT:

The double precision result is returned in AC0 (high order) and AC1 (low order).

CALLING SEQUENCE AND ENTRY POINT:

Indirect to .MPY with normal return to the instruction following the call.

CARRY AND REGISTERS:

AC0, AC1, AC3, and Carry are destroyed, AC2 remains unchanged.

LENGTH AND TIME:

This routine consists of 16 (octal) words and is normally relocatable.

For execution time in addition to unsigned multiply, 56.4 μ s.

For execution time in unsigned multiply, 340 μ s.

Total average execution time is 396.4 μ s.

PURPOSE:

To calculate the product of two unsigned integers or the sum of that product and a third unsigned integer (MPY).

TITLE:

MPY

ENTRIES:

MPY, .MPYU, .MPYA

INPUT:

The multiplier and multiplicand are input in AC1 and AC2 (MPY). If a third integer is to be added to the product, the integer is input in AC0.

OUTPUT:

The result is output with the high order portion in AC0 and the low order portion in AC1.

CALLING SEQUENCES:

The calling sequences consist of indirect calls through page zero entries .MPYU and .MPYA, with return to the next sequential location following the call. MPY is equivalent to JSR @ .MPYA. .MPYU is used if no third integer is to be added to the product.

ERROR CONDITIONS:

None.

CARRY AND REGISTERS:

AC2 and Carry are restored; AC0, AC1, and AC3 are destroyed.

LENGTH AND TIME:

Two ZREL locations and 14 octal NREL locations are required. Average execution times for .MPYU are 87 μ s on the Supernova and 441 μ s on the Nova. Average execution times for MPY are 86 μ s on the Supernova and 435 μ s on the Nova.

ALGORITHM:

.MPYU creates an all-zero addendum upon entry, and then enters the MPY common logic. The multiply-and-add function is performed by iteratively examining the least significant bit (LSB) of the multiplicand and then shifting the multiplicand to the right. If the LSB was a one, then the multiplier is added to an accumulating partial product

Unsigned MULTIPLY (Continued)
(Single Precision)

ALGORITHM (cont'd)

and that sum is shifted to the right. If the LSB was a zero, the accumulating partial product is simply shifted rightwards. Initially the partial product is zero in .MPYU, and is equal to the addendum in MPY. The process is carried out for 16_{10} iterations and yields the exact answer.

REFERENCE:

"How to Use the Nova Computers", section 2.2 .

Unsigned MULTIPLY (cont'd)
(Single Precision)

```
.TITLE  MPY
.ENT    MPY,.MPYU,.MPYA

.ZREL

00000-000001'.MPYA:  MPYA
00001-000000'.MPYU:  MPYU

.NREL

      006000-      MPY = JSR      @.MPYA

00000'102460 MPYU:  SUBC 0,0      ; CLEAR ACO, DON'T DISTURB
                                ; CARRY
00001'054411 MPYA:  STA 3,SAV3    ; SAVE AC3
00002'034411      LDA 3,M20      ; 16 TIMES THRU LOOP
00003'125203 MPY1:  MOVR 1,1,SNC  ; CHECK NEXT MULTIPLIER BIT
00004'101201      MOVR 0,0,SKP   ; 0, JUST SHIFT
00005'143220      ADDZR 2,0      ; 1, ADD MULTIPLICAND AND SHIFT
00006'175404      INC 3,3,SZR    ; CHECK FOR 16TH TIME THRU
00007'000774      JMP MPY1      ; NO, CONTINUE
00010'125260      MOVCR 1,1     ; YES, SHIFT LAST LOW BIT
                                ; (NOTE IT WAS COMPLEMENTED BY
                                ; FINAL INC)
00011'002401      JMP @SAV3     ; RETURN

00012'000000 SAV3:  0           ; RETURN ADDRESS
00013'177760 M20:  -20        ; -16 DECIMAL

.END      ;END OF UNSIGNED MULTIPLY
```

Signed MULTIPLY
(Double Precision)

PURPOSE:

This routine calculates the product of two signed double precision numbers.

TITLE:

The title is DMPY.

INPUT:

The double precision multiplier must be in AC0, AC1 (high order, low order). The double precision multiplicand should be stored in two consecutive words, higher order first. The location following the calling instruction (JSR) should contain the address of the high order word of the multiplicand.

OUTPUT:

The quadruple precision product is stored in four consecutive locations within the DMPY subroutine, highest order word first. AC2 contains the address of the highest order word. The sign of the product is determined by the algebraic rules for signed multiplication.

CALLING SEQUENCE AND ENTRY POINT:

Indirect to .DMPY with return to the second location after the call since the location after the call contains the address of the multiplicand.

CARRY AND REGISTERS:

All accumulators and Carry are destroyed.

LENGTH AND TIME:

This routine occupies 103 (octal) locations. Execution time is approximately 1.62 milliseconds.

REFERENCE:

"How to use the Nova Computers", section 2.2.

PURPOSE:

This routine computes $-D$ where D is a double precision two's complement integer.

TITLE:

The title is `.DNEG`.

INPUT:

A double precision, two's complement number in `AC0`, `AC1` (high order, low order).

OUTPUT:

The negative of the input is returned in `AC0` (high order), `AC1` (low order).

CALLING SEQUENCE AND ENTRY POINT:

Indirect to `.DNEG` with normal return to the instruction following the call.

ERROR CONDITIONS:

Caution: The negative of -2^{**31} cannot be represented and is returned unchanged.

CARRY AND REGISTERS:

`AC0`, `AC1`, `AC3`, and Carry are destroyed; `AC2` remains unchanged.

LENGTH AND TIME:

This routine consists of 4 words and is normally relocatable. Execution time is 13.8 μ s.

OCTAL to BINARY
(Single Precision)

PURPOSE:

This routine converts an ASCII octal character string to a binary number.

TITLE:

The title is .OBIN .

INPUT:

Input characters will be requested by calling a user-written "get a character" routine whose address must be stored in ZREL location .GTCH . This user routine must be provided. Upon return from the call, this routine should return an ASCII character, right adjusted in AC0 with bit 8 = 0. Input should be of the form:

OO...OO(break)

where "O" represents octal digits.

OUTPUT:

AC0 contains the break character, and AC1 contains the binary number (MOD 200000 octal).

CALLING SEQUENCE AND ENTRY POINTS:

Indirect to .OBIN .

It is desired to output a signal character, the calling sequence is indirect to .OBNI .

An ASCII "0" followed by a null character will be transmitted via AC0 to a user-written "put character" routine whose address must be stored in ZREL location .PTCH . In both cases, return is to the first word after the call.

ERROR CONDITIONS:

Caution: Result is N MOD 200000 (octal) e.g., 576452*
Converts to 176452.

CARRY AND REGISTERS:

AC0, AC1, AC3, and Carry are destroyed; AC2 is unchanged.

LENGTH AND TIME:

This routine consists of 42 (octal) words and is normally relocatable.

Execution time for .OBIN is $63.0 + I * 70.2 \mu s$

where I represents the number of digits in the input.

PURPOSE:

This routine computes the even parity bit over a 16-bit number and returns the bit in Carry.

TITLE:

The title is .PRTY.

INPUT:

A 16-bit number is passed in AC0.

OUTPUT:

The even parity bit over the contents of AC0 will be returned in Carry.

CALLING SEQUENCE AND ENTRY POINT:

Indirect to .PRTY with return to the word following the call.

CARRY AND REGISTERS:

AC3 and Carry are destroyed; AC0, AC1, AC2 remain unchanged.

LENGTH AND TIME:

This routine consists of 16 (octal) words and is normally relocatable.

Average execution time is 215.4 μ s.

POLYNOMIAL EXPANSION

(Single Precision)

PURPOSE:

To calculate an integer Polynomial expansion series of the form $P(x) = P_0 + P_1x^1 + P_2x^2 + \dots + P_nx^n$

TITLE:

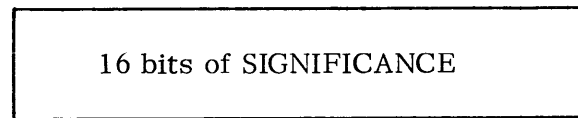
POLYN

ENTRY:

.POLY

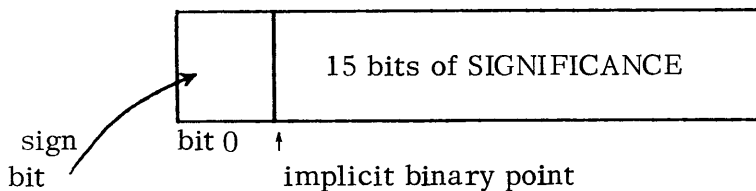
INPUT:

The order of the polynomial is input as an integer in AC1. The argument x is a positive number input in AC1 with its binary point normally to the left of bit 0, the most significant bit. (There is no sign bit reserved since all inputs must be positive.) Any shifting of the binary point is understood to shift the implicit point of the result in like fashion.

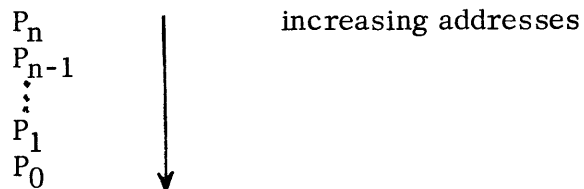


↑
implicit binary point

A pointer to the highest order coefficient is in AC0 where all coefficients are two's complement numbers, usually in the following format:



Any shifting of the binary point is understood to shift the implicit binary point of the result in like fashion. The coefficients are placed in a list with the following structure:



OUTPUT:

The result, output in AC1, is in the same format as the coefficients, with shifting of the implicit binary point as required.

CALLING SEQUENCE:

JSR indirect through page zero entry
.POLY

ERROR CONDITION:

None.

CARRY AND REGISTERS:

AC2 is saved; AC0, AC1, AC3 and Carry are destroyed.

LENGTH AND TIME:

One ZREL location and 22 octal NREL locations. Execution time depends directly upon the order of the polynomial expansion.

ALGORITHM:

A cumulative partial product is formed by successively adding the next highest order coefficient not processed to a partial product formed by x and the highest order coefficient not processed, and then by multiplying this partial sum by x . Only the most significant word of this product is retained. The process is performed iteratively, until all coefficients through P_1 have been processed. P_0 is added to the final result.

In equation form,

$$P(x) + (((P_n x) + P_{n-1})x) \dots + P_0$$

POLYNOMIAL EXPANSION (Cont'd)

(Single Precision)

PROGRAM LISTING:

; FIXED POINT POLYNOMIAL

```

; INPUT: IN AC2
;        AS A ONE WORD INTEGER
;        COEFFICIENT POINTER IN AC0
;        COEFFICIENTS IN DESCENDING POWER
;        IN TWO'S COMPLEMENT FORM
;        ORDER OF POLYNOMIAL IN AC1

```

```

; OUTPUT:      IN TWO'S COMPLEMENT
;             FORM IN AC1

```

```

.TITLE POLYN
.ENT .POLY
.EXTD MPYU

```

```

00000-000000' .POLY: .ZREL
                                POLYN
                                .NREL

```

```

00000'054417 POLYN: STA 3,PLKTN ;SAVE RETURN
00001'040417 STA 0,COEFF ;SAVE COEFF. POINTER
00002'044417 STA 1,COUNT ;AND COUNT
00003'026415 LDA 1,0COEFF ;HIGHEST COEFF
00004'121122 LOOP: MOVZL 1,0,SEC ;NEGATIVE?
00005'124440 NEGO 1,1 ;YES,MAKE IT +VE,SET CARRY
00006'006001S JSR 0,MPYU ;AC0,1 = AC1*AC2
00007'105002 MOV 0,1,SEC ;NEGATIVE SIGN?
00010'124400 NEG 1,1 ;YES,NEGATE RESULT
00011'010407 ISE COEFF ;RAISE COEFF. POINTER
00012'022406 LDA 0,0COEFF ;ADD NEXT COEFF
00013'107000 ADD 0,1 ;TO RUNNING SUM
00014'014405 DSE COUNT ;DONE?
00015'000767 JMP LOOP ;GO TO NEXT COEFF
00016'002401 JMP 0,PLKTN ;RETURN

```

```

00017'000000 PLKTN: 0
00020'000000 COEFF: 0
00021'000000 COUNT: 0

```

```

.END ;END OF POLYNOMIAL

```

PURPOSE:

This routine generates a (pseudo) random sequence of integers in the range 0 to $2^{16}-1$.

TITLE:

The title is .RAND.

INPUT:

The address of the previous random value (or initially a starting value) must be provided in the word after the call to .RAND.

OUTPUT:

The new 16-bit random result will be returned in AC0 and will also replace the previous value in memory.

CALLING SEQUENCE AND ENTRY POINT:

Indirect to .RAND followed by the address of the old value. Return will be to the instruction after the address parameter.

ERROR CONDITIONS:

Caution: If a K-bit number ($1 \leq K \leq 16$) is needed, use the most significant K bits (the least significant K bits are not as random). For example, to obtain random $N \text{ MOD } 2$, use the sign bit of the result.

CARRY AND REGISTERS:

AC0, AC3, and Carry are destroyed; AC1 and AC2 are unchanged.

LENGTH AND TIME:

This routine consists of 36 (octal) words and is normally relocatable.

Execution time is 244.7 μ s.

SINE, COSINE
(Single Precision)

PURPOSE:

To calculate the sine or cosine of an angle expressed in radians.

TITLE:

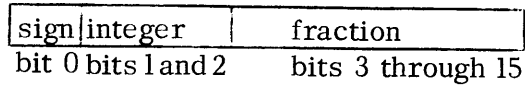
SINX

ENTRIES:

.SINX, .COSX

INPUT:

The argument m is input in AC0, within the range $-4 < n < 4$, in the following format:



The sign bit is set to a 1 only if the argument is negative.

OUTPUT:

The result is output in AC1, in the same format as the input.

CALLING SEQUENCES:

JSR indirect through either page zero entry .SINX or .COSX as appropriate.

Return is to the next sequential location following the call.

ERROR CONDITIONS:

None.

CARRY AND REGISTERS:

AC0 is saved; AC2, AC3, and Carry are destroyed.

LENGTH AND TIME:

Two ZREL and 65 octal NREL locations.

Average execution time on the NOVA 1200 is .9 ms.

ALGORITHM:

Upon entry to .COSX, m is subtracted from $\pi/2$, and the sine logic is performed on this difference. If the original argument input to .SINX is negative, the result will be equal to $-\text{SIN}(m)$; negative arguments input to .COSX will be treated as positive arguments, since $\text{COS}(-m)=\text{COS}(m)$.

Upon entry to .SINX the product of m and $2/\pi$ is calculated by means of a call to .MPYU.

The heart of the SINE logic consists of the following expansion:

$$\text{SIN} \left(\frac{m \pi}{2} \right) = m (P_0 + m (P_1 + m (P_2 + m P_3)))$$

with the following polynomial coefficients:

$$\begin{aligned} P_0 &= .15707 * 10 \\ P_1 &= -.64589 \\ P_2 &= +.79434 * 10^{-1} \\ P_3 &= -.43330 * 10^{-2} \end{aligned}$$

REFERENCE:

John F. Hart, "Computer Approximations", New York:
John Wiley & Sons, Inc., 1968; pages 116 and 117, INDEX 3300.

(Single Precision)

PROGRAM LISTING:

; FIXED POINT SIN/COS

```

      .TITLE  SINX
      .ENT    .SINX,.COSX
      .EXTD   .POLY,MPYU

      .ZREL
00000-000001' .SINX:  SINX
00001-000000' .COSX:  COSX
      .NRFL

00000'126401  COSX:  SUB      1,1,SKP      ; SET SIN/COS FLAG
00001'126520  SINX:  SUBZL     1,1
00002'044456  STA      1,SNFLG
00003'040457  STA      0,SAVE      ; SAVE INPUT
00004'054455  STA      3,RTURN     ; SAVE RETURN
00005'111120  MOVEL    0,2        ; GET SIGN
00006'125005  MOV      1,1,SNR     ; MAKE IT +VE IF COS ENTRY
00007'101020  MOVZ     0,0
00010'126560  SUBCL    1,1
00011'044453  STA      1,SIGN      ; SAVE SIGN
00012'024437  LDA      1,.20VPI   ; GET 2/PI
00013'006002$ JSR      0,MPYU           ; AC0,1 = AC1*AC2
00014'125120  MOVEL    1,1        ; PUSH OUT INTEGER PART
00015'101100  MOVL     0,0
00016'152560  SUBCL    2,2
00017'125120  MOVEL    1,1
00020'101100  MOVL     0,0
00021'151100  MOVL     2,2        ; AC2 IS INTEGER PART
00022'014436  DSE      SNFLG     ; SINE?
00023'151400  INC      2,2        ; NO, INCREMENT INTEGE
00024'151222  MOVER    2,2,SEC    ; ODD INTEGER PART?
00025'100000  COM      0,0        ; YES, COMPLIMENT FRACTION
00026'151232  MOVER#   2,2,SEC    ; ODD INTEGER/?
00027'010435  ISE      SIGN      ; YES CHANGE SIGN
00030'111000  MOV      0,2        ; FRACTION IN AC2
00031'050432  STA      2,SAVE     ; SAVE X
00032'105000  MOV      0,1
00033'006002$ JSR      0,MPYU           ; X**2

```

SIN/COS PROGRAM LISTING (cont'd):

```

00034'111000      MOV      0,2
00035'020416      LDA      0,SNCOF      ;AC0 POINTS TO COEFF.S
00036'024414      LDA      1,CFCNT      ;ORDER OF POLYNOMIAL
00037'006001S     JSR      0,POLY        ;EVALUATE POLYNOMIAL
00040'030423      LDA      2,SAV2
00041'006002S     JSR      0,MPYU
00042'151220      MOVZK    2,2
00043'143220      ADDZK    2,0
00044'024420      LDA      1,SIGN
00045'125220      MOVZK    1,1      ;GET SIGN IN CARRY
00046'105200      MOVZK    0,1      ;PUSH INTO RESULT
00047'020413      LDA      0,SAV0      ;RESTORE INPUT ARGUMENT
00050'002411      JMP      0,RTURN      ;RETURN TO CALL+1

```

```

00051'121377      .20VPI: 121377 ;2/PI(.505746 OCTAL,TWEAKED)
00052'000003      CFCNT: 3
00053'000054      SNCOF:  .+1
00054'177562      -216      ;-.0043331
00055'005053      5053      ;.0794343
00056'126524      -51254    ;-.6458928
00057'044420      44420     ;1.570791(ADD 1 LATER)

```

```

00060'000000      SNFLG:  0
00061'000000      RTURN:  0
00062'000000      SAV0:  0
00063'000000      SAV2:  0
00064'000000      SIGN:  0

```

```

      .END      ;END OF SINX,COSX

```

SORT

PURPOSE:

This routine sorts a table of pairs of words so that the first words of the pairs are in ascending order.

TITLE:

The title is RSORT.

INPUT:

A table containing pairs of words; the first word of each pair, the key word, must be an unsigned integer. AC1 must contain the starting address of the table; AC2 must contain the ending address of the table.

OUTPUT:

A table of pairs of words, sorted so that the key words are in ascending order. The key word and its accompanying data word are unchanged by the sort.

CALLING SEQUENCE AND ENTRY POINT:

Direct to RSORT with normal return to the instruction following the call.

CARRY AND REGISTERS:

AC0, AC3, and Carry are destroyed; AC1 and AC2 are unchanged.

LENGTH AND TIME:

This routine consists of 127 (octal) words and is normally relocatable. Execution time is approximately .3 seconds for a table containing 1000 pairs of words.

PROGRAM LISTING:

0001 RSORT

```

;ROUTINE TO SHUFFLE A TABLE OF PAIRS OF WORDS
;SO THE FIRST WORDS OF THE PAIRS(KEY WORDS)
;ARE IN ASCENDING ORDER.
;KEY WORD-DATA WORD PAIRING LEFT UNCHANGED.
;KEY WORDS UNSIGNED INTEGERS.

```

```

;CALLING SEQUENCE:

```

```

;(LOAD IN AC1 STARTING ADDRESS OF TABLE
;AND ADDRESS OF THE LAST WORD OF TABLE IN AC2)
;      JSR  RSORT
;      RETURN

```

```

;TYPICAL TIME: .3 SEC FOR 1000 PAIRS

```

```

.TITLE  RSORT
.ENT    RSORT
.NREL

```

```

00000'000460  RSORT:  LDA    0,0,STAK           ;SET UP STACK POINTER
00001'000460          STA    0,0,STAK
00002'100620          SUB#R  0,0           ;SET BIT 0
00003'010456  SORT1:  TSE    STAK
00004'056455          STA    3,0,STAK           ;SAVE RETURN
00005'010454          TSE    STAK
00006'052453          STA    2,0,STAK           ;SAVE HIGH POINTER
00007'135000          MOV    1,3           ;LOW POINTER
00008'0024452        LDA    1,C2
00009'167000          ADD    3,1
00010'132112        ADCL#  1,2,SEC           ;SCAN COMPLETE?
00011'000444          JMP    SORT6           ;YES
00012'054447          STA    3,TEMP           ;SAVE LOW POINTER
00013'025400  SORT2:  LDA    1,0,3
00014'123415          AND#   1,0,SNR           ;LOW KEY BIT SET?
00015'000423          JMP    SORT3           ;NO
00016'024442          LDA    1,C2
00017'132400          SUR    1,2           ;DROP HIGH POINTER
00018'025000          LDA    1,0,2
00019'123414          AND#   1,0,SZR           ;HIGH KEY BIT SET?
00020'000415          JMP    SORT4           ;YES, NO SWAP
00021'040437          STA    0,BIT           ;SAVE COMPARISON BIT
00022'021400          LDA    0,0,3
00023'025000          LDA    1,0,2           ;SWAP KEY WORD-DATA WORD PAIRS

```

SORT (cont'd)

PROGRAM LISTING (cont'd):

```

00030'041000      STA      0,0,2
00031'045400      STA      1,0,3
00032'021401      LDA      0,1,3
00033'025001      LDA      1,1,2
00034'041001      STA      0,1,2
00035'045401      STA      1,1,3
00036'020426      LDA      0,BIT      ;RECOVER COMPARISON BIT
00037'024423  SORT3:  LDA      1,C2
00040'137000      ADD      1,3      ;BUMP LOW POINTER
00041'156414  SORT4:  SUB#    2,3,SZ#   ;SCAN OVER?
00042'000753      JMP      SORT2      ;NO,CONTINUE
00043'101222      MOVZ#   0,0,SZ#   ;ALL BIT POSITIONS COVERED?
00044'000406      JMP      SORT5      ;YES
00045'024416      LDA      1,TEMP    ;NO,NEXT BIT
00046'004735      JSR      SORT1
00047'032412      LDA      2,@STAK
00050'004733      JSR      SORT1
00051'101121      MOVZL   0,0,SKP
00052'101100  SORT5:  MOVL    0,0
00053'026406  SORT6:  LDA      1,@STAK
00054'014405      DSZ     STAK
00055'036404      LDA      3,@STAK
00056'014403      DSZ     STAK
00057'001400      JMP      0,3

00060'000065' .STAK:  STAK0
00061'000000  STAK:   0
00062'000002  C2:     2
00063'000000  TEMP:   0
00064'000000  BIT:     0

000042  STAK0:  .BLK   42

                                .END      ;END OF RADIX EXCHANGE SORT

```

PURPOSE:

This routine calculates the square root of an unsigned single precision integer.

TITLE:

ISQRT

ENTRY:

.ISQR

INPUT:

An unsigned fixed point number is input in AC0.

OUTPUT:

The square root of the input, truncated to the nearest integer, is output as an integer in AC1. Accuracy is to within one binary digit.

CALLING SEQUENCE AND ENTRY POINT:

Indirect through page zero entry .ISQR with return to the next sequential instruction following the call.

ERROR CONDITIONS:

There are no error conditions. All input values are acceptable as unsigned integers.

CARRY AND REGISTERS:

AC0, AC2, AC3, and Carry are destroyed.

LENGTH AND TIME:

This routine consists of 1 ZREL and 24 octal NREL locations. Average execution time is 82.4 μ s on both the Supernova and Nova 800, and 153 μ s on the Nova 1200. Average execution time on the Supernova SC is 60.5 μ s.

ALGORITHM:

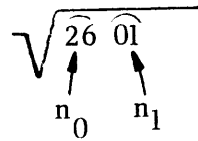
One of three different algorithms is usually selected when extracting a square root: the sum of odd integers method, Newton's iterative method of successive approximations, and the longhand partial quotient procedure. The partial quotient procedure was selected for this subroutine.

The partial quotient method of square root extraction is the same as the pencil-and-paper procedure commonly used to extract square roots of decimal numbers. In this method the number n whose root is to be extracted, is first paired off in groupings of two digits each ($n_0 n_1$, etc.)

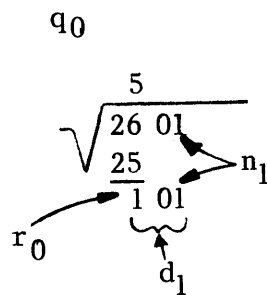
Unsigned SQUARE ROOT (cont'd)

(Single Precision)

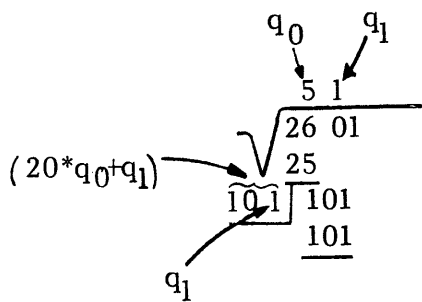
ALGORITHM (cont'd) :



The largest integer root less than or equal to the exact root of n_0 is selected, q_0 , and becomes the most significant digit of the extracted root. q_0 is squared and is subtracted from the first pair, yielding remainder r_0 .



r_0 is multiplied by 100 and is added to n_1 , forming a new partial dividend, d_1 (the first partial dividend, d_0 equaled n_0 , the first pair of digits). d_1 is divided by $20 * q_0 + q_1$, where q_1 is the largest possible integer such that $q_1 * (20 * q_0 + q_1) \leq d_1$. The process is repeated with each partial dividend until all digits in n have been processed.



The subroutine algorithm is similar to that described above, but is modified to process 16-bit unsigned binary numbers instead of real decimal numbers. The subroutine considers n as 8 pairs of binary digits and repeats its procedure 8 times.

ALGORITHM (cont'd):

This algorithm was selected since its use results in the most efficient coding and fastest execution time for the complete range of permissible input values for all Nova family machines.

The sum of odd integers method given in "How to Use the Nova Computers" yields more efficient coding and faster execution times when input arguments are no greater than 1000_{10} . Over the whole range of permissible inputs however, its average execution time is $412 \mu\text{s}$ on the Supernova.

Newton's method requires either the use of hardware divide or the software divide subroutines, and its average execution time over the entire permissible range of inputs is $114 \mu\text{s}$ on the Supernova (with hardware divide).

REFERENCE:

Section 2.2 of "How to Use the Nova Computers" contains a discussion of the sum of odd integers method of square root extraction.

Unsigned SQUARE ROOT (cont'd)
 (Single Precision)

PROGRAM LISTING:

```

---
0001  ISORT
; SQUARE ROOT OF AN UNSIGNED INTEGER
; INTEGER ARGUMENT IN AC0
; OUTPUT: SQUARE ROOT TRUNCATED TO NEAREST
; INTEGER RETURNED IN AC1
; REGISTERS AND CARRY DESTROYED

; CALLING SEQUENCE:
;     JSR     @.ISORT
;     RETURN LOCATION

      .TITLE  ISORT
      .ENT   .ISQR

      .ZREL
00000-000002'.ISQR: ISORT
      .NREL

00000'000000 RTRN:  0      ; RETURN ADDRESS
00001'000000 COUNT: 0      ; COUNTING LOCATION
00002'054776 ISORT: STA    3,RTRN ; SAVE RETURN ADDRESS
00003'024420      LDA    1,C8   ; SET UP COUNT *
00004'044775      STA    1,COUNT
00005'126400      SUB    1,1   ; CLEAR PARTIAL QUOTIENT
00006'152400      SUB    2,2   ; AND REMAINDER

00007'101120 ISQ1:  MOVZL  0,0   ; ADD (NEXT) HIGHEST
00010'151100      MOVL   2,2   ; TWO BITS OF ARG. TO
00011'101120      MOVZL  0,0   ; FOUR TIMES PARTIAL REMAINDER
00012'151100      MOVL   2,2   ; TO GET NEW PARTIAL DIVIDEND
00013'135120      MOVZL  1,3   ; NEW QUOTIENT IS TWICE THE OLD ONE
00014'175140      MOVOL  3,3   ; IF TWICE NEW QUOTIENT+1 (DIVISOR)
00015'172432      SUBZ#  3,2,SZC ; IS EQUAL TO OR LESS THAN
00016'172420      SUBZ   3,2   ; THE DIVIDEND, INCREMENT
00017'125100      MOVL   1,1   ; QUOTIENT AND SUBTRACT
00020'014761      DSZ   COUNT ; DIVISOR FROM DIVIDEND
00021'000766      JMP    ISQ1  ; TO GET NEW REMAINDER
00022'002756      JMP    @RTRN ; AND REPEAT 7 MORE TIMES

00023'000010 C8:   10      ; EIGHT

      .END   ; END OF SORT(INTEGER)

```

```

---
0002  ISORT

```

C8	000023'	1/19	1/37	
COUNT	000001'	1/17	1/20	1/33
ISQ1	000007'	1/24	1/34	
ISORT	000002'	1/14	1/18	
RTRN	000000'	1/16	1/18	1/35
.ISQR	000000-	1/14		

PURPOSE:

This routine calculates the square root of an unsigned double precision integer, and expresses the result as a truncated single precision integer.

TITLE:

DISQR

INPUT:

An unsigned double precision fixed point number is input in AC0 and AC1 (more significant half in AC0).

OUTPUT:

The square root of the input, truncated to the nearest integer, is output as an integer in AC2. Accuracy is to within one binary digit.

CALLING SEQUENCE AND ENTRY POINT:

Indirect through page zero entry .DISQ with return to the next sequential instruction following the call.

ERROR CONDITIONS:

There are no error conditions. All input values are acceptable as unsigned integers.

CARRY AND REGISTERS:

AC0, AC1, AC3, and Carry are destroyed.

LENGTH AND TIME:

This routine consists of 1 ZREL and 16 octal NREL locations. Average execution time on the Nova 1200 with software divide is 6 ms.

ALGORITHM:

Initially a trial square root of 177777 octal is assumed. An integer division of the input argument by this trial square root is then performed, and the arithmetic mean of this quotient and the trial root is calculated, yielding a new trial root. The process of dividing the new trial root by the input argument continues until the new root differs by less than two from the next most recent trial root.

Unsigned SQUARE ROOT (cont'd)

(Double Precision)

PROGRAM LISTING:

0001 DISQR

```
;SQUARE ROOT OF AN UNSIGNED TWO WORD INTEGER
;INPUT INTEGER IN AC0,1
;RESULT (TRUNCATED TO NEAREST )INTEGER IN AC2
;ACCUMULATORS AND CARRY LOST
```

```
;CALLING SEQUENCE:
```

```
;
;
;
;------(LOAD INTEGER IN AC0 AND AC1)
; JSP @.DISQ
; RESULT LOCATION
```

```
;RANGE OF ARGUMENT 0 TO (2**16-1)**2
;NO ERROR MESSAGES
;SUPPORTING ROUTINE DVD
;(UNSIGNED SINGLE PRECISION INTEGER DIVIDE)
```

```
.TITLE DISQR
.ENT .DISQ
.EXTN DVD
```

```
00000-000003'.DISQ: .ZREL
DISQR
.NREL
```

```
00000'000000 INTG0: 0
00001'000000 INTG1: 0
00002'000000 PTRN: 0
```

```
00003'054777 DISQR: STA 3,RTN ;SAVE RETURN ADDRESS
00004'040774 STA 0,INTG0 ;SAVE HIGH WORD
00005'044774 STA 1,INTG1 ;AND LOW WORD
00006'152000 ADC 2,2 ;TRIAL ROOT SET 177777(OCCIAL)
```

```
00007'020771 DISQ1: LDA 0,INTG0
00010'024771 LDA 1,INTG1 ;LOAD ARGUMENT
00011'177777 DVD ;DIVIDE IT BY TRIAL ROOT
00012'133220 ADDZP 1,2 ;TAKE THE MEAN OF QUOTIENT AND
00013'146654 SUBOR# 2,1,SZF ;TRIAL ROOT TO IMPROVE ROOT
00014'000773 JMP DISQ1 ;IF NEW ROOT DIFFERS BY LESS
00015'002765 JMP @RTN ;THAN TWO FROM QUOTIENT, RETURN
```

```
.END ;END OF SQUARE ROOT OF INTEGER
```


PURPOSE:

This routine computes the difference of two double precision two's complement integers.

TITLE:

The title is .DSUB.

INPUT:

The minuend is passed in AC0, AC1, (high order, low order). The subtrahend must be in two consecutive memory words, higher order followed by lower order. The word following the JSR should contain the address of the higher order word of the subtrahend.

OUTPUT:

The double precision difference is returned in AC0, AC1 (high order, low order).

CALLING SEQUENCE AND ENTRY POINT:

Indirect to .DSUB followed by the address of higher order word of subtrahend. Return will be to the instruction following the address parameter.

ERROR CONDITIONS:

Caution: No check is made for overflow.

CARRY AND REGISTERS:

AC0, AC1, AC3, and Carry are destroyed; AC2 remains unchanged.

LENGTH AND TIME:

This routine is 15 (octal) words and is normally relocatable. Execution time is 54.9 μ s.

CHANGES FROM REVISION 2 TO REVISION 3 OF THE RELOCATABLE MATH
LIBRARY FILE MANUAL

Substantive changes are described in the following list. Typographical corrections are not included.

- Page 19 Signed double precision division is now performed by the routine DMPY.
- Page 30 Signed double precision multiplication is now performed by the routine DDIV. The descriptions of DDIV and DMPY (page 19) replace that of .DPMD.
- Page 42 A description of RSORT, which sorts pairs of words in ascending order, has been added.

Some character conversion routines now require a "get a character" and/or "put a character" routine whose address must be stored in ZREL locations .GTCH and .PTCH, respectively. This change is reflected in the following pages: 12, 13, 15, 16, and 17.

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