

UNIVERSITY OF ILLINOIS  
DIGITAL COMPUTER

AUXILIARY  
LIBRARY ROUTINE E 11-- 311

TITLE: Evaluation of Exponentially Weighted Infinite Integrals by Quadrature (Hermite Quadrature)  
 TYPE: Closed subroutine, with one program parameter  
 NUMBER OF WORDS: 18 + 2N (see below)  
 DURATION: N(1.8 + T) milliseconds, where T is the duration in milliseconds of the auxiliary subroutine.  
 TEMPORARY STORAGE: Location 0 (may be used by auxiliary subroutine)  
 ENTRY: When this routine is located at y, entry is made by the orders

$$\begin{array}{r|l} p & \text{-- aF} \\ \hline & 50 \text{ pF} \\ p + 1 & 26 \text{ yF} \end{array},$$

where a is the location of the auxiliary subroutine which computes the values of the function to be integrated. When control is returned to the right side of p + 1, the computed integral will be in the accumulator register and location y + 14.

DESCRIPTION: To evaluate the integral

$$\int_{-\infty}^{\infty} e^{-x^2} f(x) dx,$$

this routine uses a form of Gaussian Quadrature appropriate to the interval  $(-\infty, \infty)$  and the weighting function  $e^{-x^2}$ :

$$\int_{-\infty}^{\infty} e^{-x^2} f(x) dx \approx \frac{1}{2^P} \sum_{k=1}^N A_k f(x_k). \quad (1)$$

The values  $A_k$  and  $x_k$  are chosen in a manner such as to give min truncation error when  $f(x)$  is a polynomial of degree  $2N - 1$  or less. In the case where the factor  $e^{-x^2}$  does not occur explicitly in the integrand,

$$\int_{-\infty}^{\infty} g(x) dx = \int_{-\infty}^{\infty} e^{-x^2} [e^{x^2} g(x)] dx \approx \frac{1}{2^Q} \sum_{k=1}^N A_k e^{-(x_k)^2}$$

$$g(x_k) = \frac{1}{2^Q} \sum_{k=1}^N B_k g(x_k). \quad (2)$$

It is assumed that the function  $e^{x^2} g(x)$  may be closely approximated by a polynomial function.

Because the actual values of the points  $x_k$  and the weights  $A_k$  and  $B_k$  may exceed 1, they have been scaled down by powers of two. P and Q are defined in equations (1) and (2), and R is defined below in equation (3).

N	R	P(for $A_k$ )	Q(for $B_k$ )
1	0	1	1
2	0	0	1
3	1	1	1
4	1	0	1
5	2	0	1
6	2	0	1
7	2	0	1
8	2	0	1
9	2	0	1
10	2	0	1
11	2	0	1
12	2	0	0
13	3	0	0
14	3	0	0
15	3	0	0
16	3	0 (see note)	0
17	3	0 "	0
18	3	0 "	0
19	3	0 "	0
20	3	0 "	0

[Note: Because the weights for these values of N become quite small, there may be appreciable roundoff errors for certain integrands].

The auxiliary subroutine which computes  $f(x_k)$  must take the scaling of these values of  $x_k$  into account. The function values computed by the auxiliary are assumed to lie in the range  $-1 \leq f(x_k) < 1$ .

The closed auxiliary subroutine is entered from the main routine with  $x_k^*$  in the accumulator and link in Q; control is returned to the main routine with  $f(x_k)$  in the accumulator.

USE:

To use this routine the programmer copies the integration routine first on his program tape, and immediately after it the parameters, points  $x_k$ , and weights  $A_k$  or  $B_k$  appropriate to his needs. These latter numbers appear on the tail of the library tape, labeled by the number N of points at which the function is to be evaluated, and the type of weights ( $A_k$  or  $B_k$ ) to be used.

SCALING:

The scaling of the values of  $x_k$  is such that the auxiliary subroutine is presented with  $x_k^*$ , where

$$x_k^* = 2^{-R} x_k, \quad 0 \leq R \leq 3, \quad (3)$$

and the largest  $x_k^*$  satisfied  $1/2 \leq (x_k^*)_{\max} < 1$  for all N.

The computed integral is scaled down by  $2^P$  (or  $2^Q$ ).

For the convenience of the programmer, the above scale factors are contained in the subroutine parameter at location  $y + 16$ , in the following form:

$(y+16) = OR (y+18) OP (y+18+N),$	for A weights
$= OR (y+18) OQ (y+18+N)$	for B weights.

ACCURACY:

The truncation error due to omission of powers of x higher than 2N is

$$\frac{n! \sqrt{\pi}}{2^n (2n)!} f^{(2n)}(z), \quad \text{where } z \text{ is some point in } (-\infty, \infty).$$

There will also be round-off errors which may be significant; for a discussion of these see the write-up of library routine E 5 - 195.

REFERENCES:

National Bureau of Standards Journal of Research, Vol. 48,  
p. 111 (1952).

G. Szegő, Orthogonal Polynomials.

F. G. Tricomi, Vorlesungen über Orthogonalreihen

DATE	<u>October 12, 1960</u>
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LOCATION	ORDER	NOTES	PAGE 1	E 11
	00 K			
0	L5 16L	Preset point and weight addresses		
	46 5L			
1	42 7L			
	K5 F			
2	46 6L	Plant subroutine entry and link		
	42 13L			
3	41 14L	clear sum box		
	2S 4L			
4	S5 F	Save L.S.P. of sum		
	40 15L			
5	L5 ( )F	get $x_k^*$ ; link to Q		
	50 5L			
6	26 ( )F	jump to auxiliary		
	40 F			
7	L5 15L	L.S.P. to A, weight in Q		
	50 ( )F			
8	74 F	$x f(x_k)$ , accumulate M.S.P.		
	L4 14L			
9	40 14L			
	L5 8L			
10	L4 5L	step $x_k$ address		
	46 5L			
11	F5 7L	step $A_k$ address		
	42 7L			
12	L0 17L			
	36 4L			
13	L5 14L	exit via link		
	22 ( )F			
14	00 F	temporary store for M.S.P.		
	00 F			
15	00 F	" " " L.S.P.		
	00 F			
16	OR 18L			
	OP [18+N]L	Coefficient addresses and scale constants		

LOCATION	ORDER	NOTES	PAGE 2	ELL
17	75 15L	end constant		
	50 [18+2N]L			
18	$x_1^*$			
.	.			
.	.			
.	.			
17+N	$x_N^*$			
18+N	$A_1$ or $B_1$			
.	.			
.	.			
.	.			
17+2N	$A_N$ or $B_N$			